

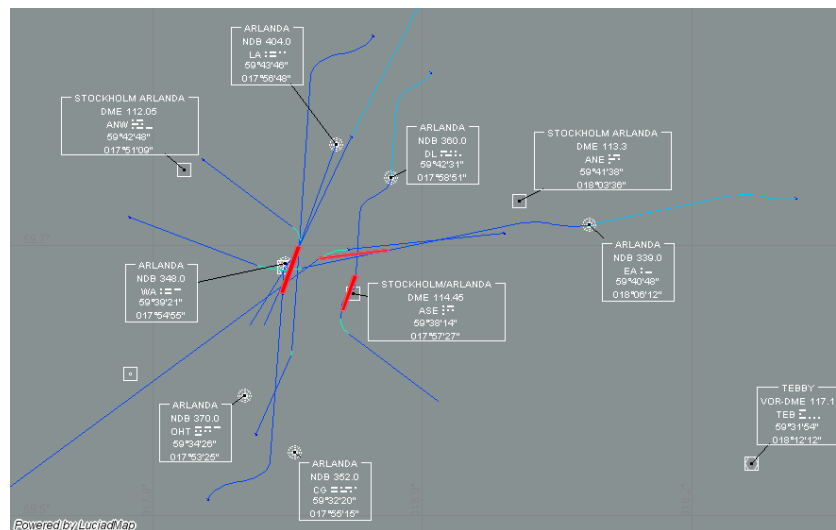
Luciad introduction

- **Software components for high performance visualization**
- **Key domains: Aviation, Defense and Security**
- **Adoption of aeronautical standards**
 - ARINC 424-13, 424-15, 424-18
 - AIXM 3.3, 4.0, 4.5, 5.0, 5.1
 - DAFIF Edition 7 and 8
 - ASTERIX
 - ASDI



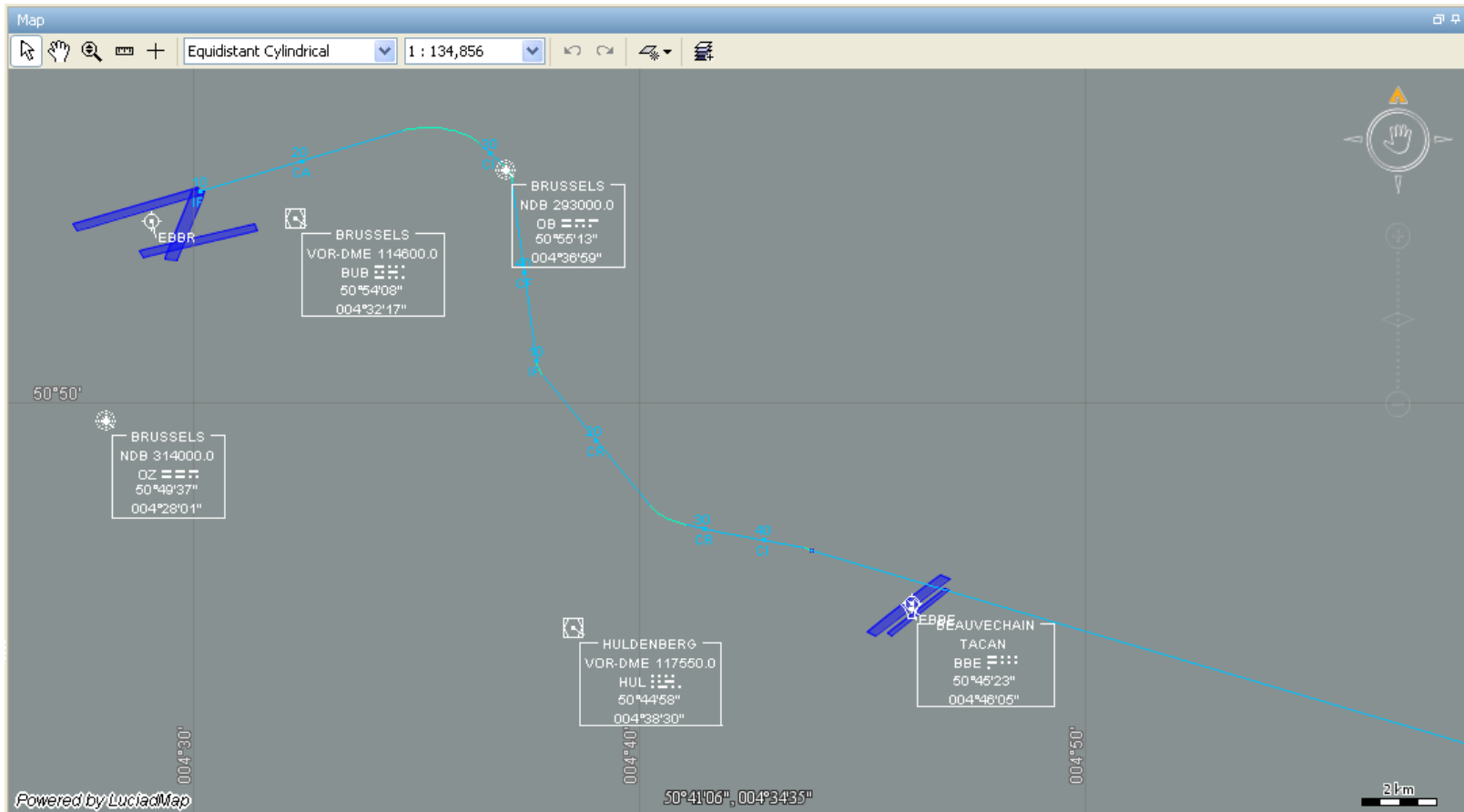
Path and Terminator support (ARINC)

- **Adopted by ARINC 424, AIXM, DAFIF**
- **Software implementation**
 - Domain model to represent decoded procedure / procedure leg data
 - Algorithm to calculate the actual aircraft trajectory
 - Based upon procedure leg information
 - Taking into account aircraft performance settings



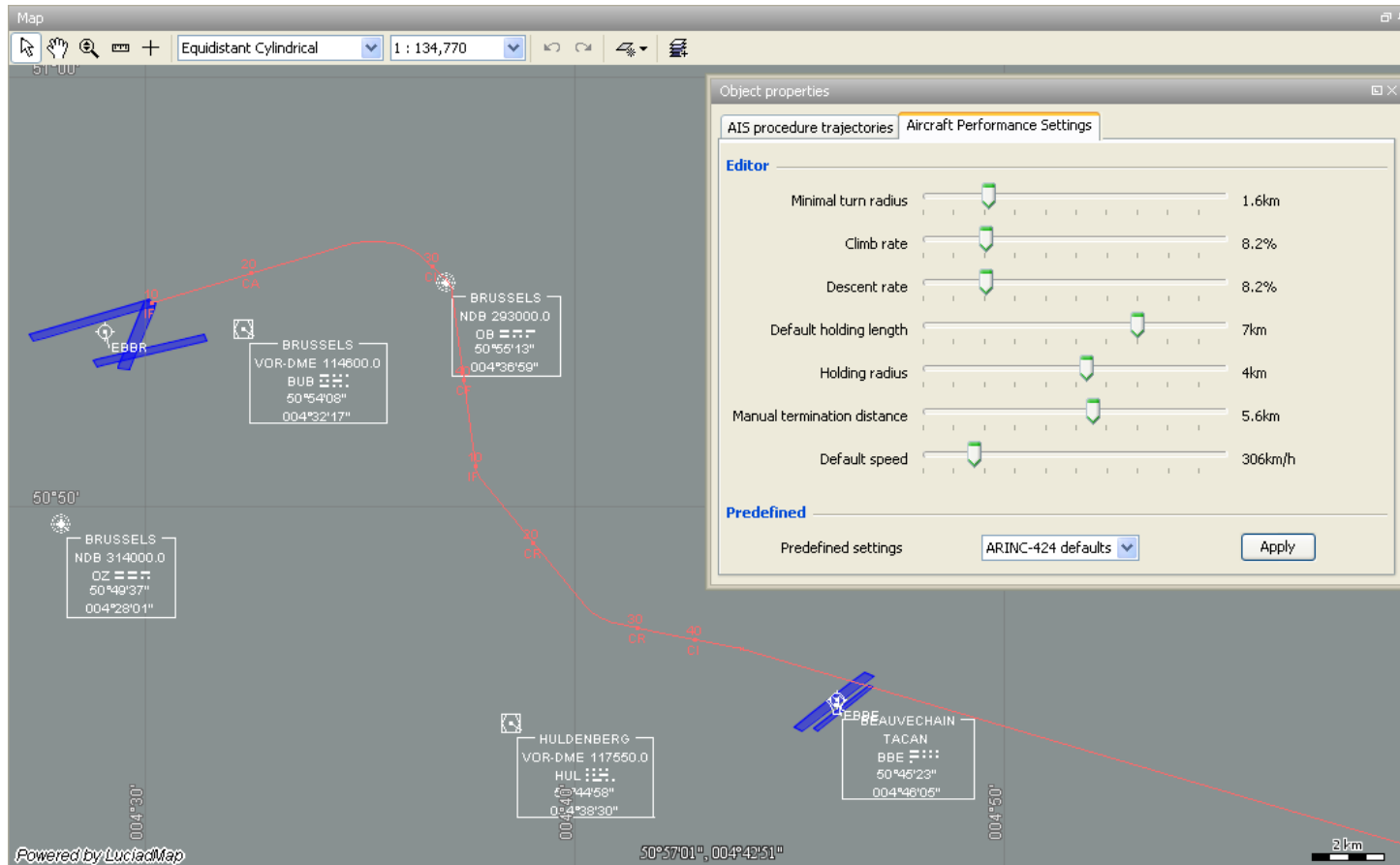
Procedure trajectory calculation example (1)

© 2010 Luciad. Do not use outside AIXM5 procedure seminar without permission of Luciad (info@luciad.com)



Procedure trajectory calculation example (2)

© 2010 Luciad. Do not use outside AIXM5 procedure seminar without permission of Luciad (info@luciad.com)



Path and Terminator support (ARINC)

■ Advantages

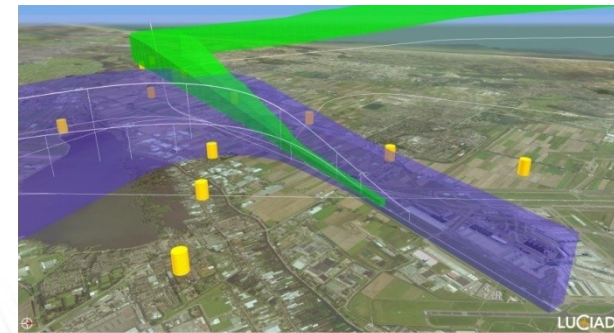
- Reduced number of waypoints
- Close match with procedure charts
- Decoupling of aircraft performance settings (e.g., convenient for simulation)

■ Disadvantages

- Calculation of the aircraft trajectory on a map (e.g., for simulation) is complex and costly
 - >> 20 procedure leg types
 - Complex procedures are easy to misinterpret
- No performance model in most data formats

AIXM 5.x procedure support

- **New procedure model**
 - Procedure leg (path and terminator) modeling
 - Procedure trajectory (geometry) encoding
 - Performance model
- **More flexibility to support procedures**
 - Direct visualization of procedure trajectory
 - Useful for simple web clients or a quick preview
 - More advanced operations (analysis, simulation, ...) possible through procedure leg/performance model information



AIXM 5.x procedure support

Experiments

- Data conversions from ARINC to AIXM 5.1
 - No real-world testdata yet
- Procedure generation using both ARINC leg type information and calculated trajectory

Demonstrations in OGC OWS-6 and OWS-7

```
<aixm:DepartureLegTimeSlice>
  <aixm:interpretation>BASELINE</aixm:interpretation>
  <aixm:legTypeARINC>CF</aixm:legTypeARINC>
  <aixm:course>87.05139231681824</aixm:course>
  <aixm:upperLimitAltitude uom="M">914.40</aixm:upperLimitAltitude>
  <aixm:lowerLimitAltitude uom="M">914.40</aixm:lowerLimitAltitude>
  <aixm:altitudeInterpretation>AT_LOWER</aixm:altitudeInterpretation>
  <aixm:endPoint>
    <aixm:TerminalSegmentPoint>
      <aixm:pointChoice_position>
        <aixm:Point>
          <gml:pos>-2.2255555555555557 49.476944444444445</gml:pos>
        </aixm:Point>
      </aixm:pointChoice_position>
    </aixm:TerminalSegmentPoint>
  </aixm:endPoint>
  <aixm:trajectory>
    <aixm:Curve>
      <gml:segments>
        <gml:LineStringSegment>
          <gml:posList>-2.2308943264287695 49.47676513538419
            -2.6477318124656692 49.462000110733754</gml:posList>
        </gml:LineStringSegment>
        <gml:ArcByCenterPoint>
          <gml:posList>-2.2297685267287077
            49.462452209403885</gml:posList>
          <gml:radius>1593.956776712</gml:radius>
          <gml:startAngle>1.622004315725133</gml:startAngle>
          <gml:endAngle>1.1445247816121895</gml:endAngle>
        </gml:ArcByCenterPoint>
      </gml:segments>
    </aixm:Curve>
  </aixm:trajectory>
</aixm:DepartureLegTimeSlice>
```

Conclusions

- **How to ensure data quality?**
 - XML schema allows too many degrees of freedom.
 - What data should always be available?
 - How to avoid ambiguities, conflicts?
 - e.g. not all leg types can occur everywhere.
- **Extensive model increases readability**
 - Compared with record data formats like ARINC
 - Equally extensive documentation can influence data quality